

# \_Helios2 Time of Flight (ToF) IP67 3D Camera



Sensor	Resolution	Frame Rate	
Sony DepthSense IMX556 CMOS	0.3 MP 640 x 480 px	30 FPS	

Model SKUs	Chroma	Working Distance	IP Rating	GigE Vision Connector	Included Accessory
HLT003S-001	Mono	0.3 m to 8.3 m	IP67	M12	M8 GPIO IP67 Cap

## **Specifications**

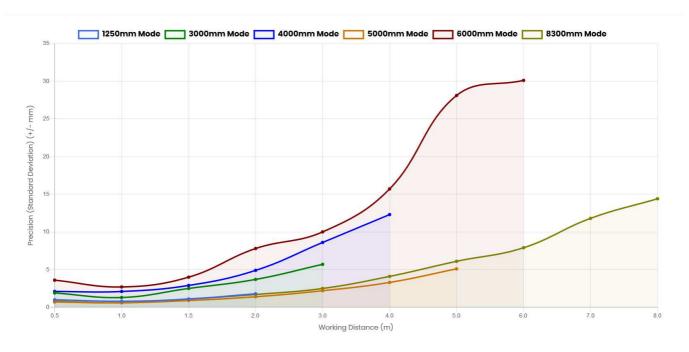
Illumination

	Interface and Power Information			
Digital Interface 1000BASE-T GigE, M12 X-coded, PoE				
GPIO Interface 8 pin M8 connector				
Opto-Isolated I/O Ports	1 input (2.5V-24V and 10.5V-24V), 1 output			
Non-Isolated I/O Ports	2 bi-directional			
Power Requirement	PoE+ (IEEE 802.3at) or 18-24 V through GPIO			
Power Consumption	12-24Vdc, P <sub>avg</sub> <12W, <30W peak power			
Sensor Properties				
Sensor Model	Sony DepthSense IMX556PLR CMOS			
Shutter Type	Global			
Sensor Size	8 mm (Type 1/2")			
Resolution	640 x 480 px, 0.3 MP			
Pixel Size	10.0 μm (H) x 10.0 μm (V)			
Framerate	30 FPS @ 0.3 MP (for all operating modes)			
Physical Properties				
Dimensions	60 x 60 x 77.5 mm			
Weight	398 g			
Ingress Protection	IP67 (For IP67 protection Helios2 must be used with IP67 cables)			
Ambient Light Filter	mbient Light Filter Yes, integrated on-camera			
Lens Field of View 69° x 51° (nominal)				

4 x VCSEL laser diodes, Class 1, @ 850nm

	Standard and Certifications			
Standard	GigE Vision v2.0, GenICam 3D			
Compliance	CE, FCC, RoHS, REACH, WEEE,			
Compilance	Eye Safety Class 1 IEC/EN 60825-1:2014			
Operating Temperature	-20° to 50°C (Case Temperature)			
Shock and Vibration	DIN EN 60068-2-27, DIN EN 60068-2-64			
Industrial EMC Immunity	DIN EN 61000-6-2			
OS Support	Windows and Linux			
Software Support	Arena SDK, C++, C, C#, Python			
	Pixel Formats			
Range Data				
Coord3D_ABCY16	4-ch point cloud XYZ + Intensity, 16 bits per channel, unsigned			
Coord3D_ABC16	3-ch point cloud XYZ, 16 bits per channel, unsigned			
Coord3D_C16	Depth map Z plane, 16 bits, unsigned			
Intensity Image				
Mono8	8 bit per pixel monochrome raw image			
Mono12Packed	12 bit per pixel monochrome raw image			
Mono12p	12 bit per pixel in bit stream, monochrome raw image			
Mono16	16 bit per pixel monochrome raw image			
Confidence Data				
Confidence16	Confidence map, 16 bits			
	Imaging Properties			
Exposure Control	Manual, 3 settings: 62.5 μs, 250 μs or 1000 μs			
Gain Control	Manual, 2 settings: High or Low			
Synchronization	Software trigger, hardware trigger, PTP (IEEE 1588)			
Output Format	Binary .PLY file (via Arena SDK)			
Camera Features				
User Sets Working Distance Operating Distance Modes	1 default and 2 custom user set 0.3 m to 8.33 m 6 Modes: (1) 1250 mm, (2) 3000 mm, (3) 4000 mm, (4) 5000 mm, (5) 6000 mm, (6) 8333 mm			
Accuracy	See Performance Tab			
Precision (Depth Noise)	See Performance Tab			
Communication Channels	5 Channels Allows users to operate up to 5 Helios2 cameras without			
Flying Pixel Filter	Yes			
Intrinsic parameters avail	able			
Intrinsic parameters avail	able			

## **Performance**



### **Helios2 Accuracy**

Distance (m)	Accuracy	
1250mm Mode (up to 1.25m)	± 4 mm	
3000mm Mode (up to 3.0m)	± 10 mm	
4000mm Mode (up to 4.0m)	± 10 mm + 0.25% of depth	
5000mm Mode (up to 5.0m)	± 4 mm + 0.1% of depth	
6000mm Mode (up to 6.0m)	± 10 mm + 0.5% of depth	
8300mm Mode (up to 8.3m)	± 4 mm +0.2% of depth	

#### **Helios2 Precision**

Distance (m)	1250mm Mode	3000mm Mode	4000mm Mode	5000mm Mode	6000mm Mode	8300mm Mode
0.5*	1.0 mm	1.9 mm	2.1 mm	0.7 mm	3.6 mm	0.8 mm
1	0.8 mm	1.3 mm	2.1 mm	0.6 mm	2.7 mm	0.6 mm
1.5	1.1 mm	2.5 mm	2.9 mm	0.9 mm	4.0 mm	1.1 mm
2	1.8 mm	3.7 mm	4.9 mm	1.4 mm	7.8 mm	1.7 mm
3		5.7 mm	8.6 mm	2.2 mm	10.0 mm	2.5 mm
4			12.3 mm	3.3 mm	15.7 mm	4.1 mm
5				5.1 mm	28.1 mm	6.1 mm
6					30.1 mm	7.9 mm
7						11.8 mm
8						14.48 mm

<sup>\*0.5</sup> m distance precision measured with 250 μs exposure time, all other distances using 1000 μs exposure time measured with white paper target.

#### **Test Conditions:**

- Target: White paper mounted on bar attached to motion stage
- Helios2 positioning: mounted on tripod, laser distance meter used to measure distance from case front to stage zero position
- Camera setting: Coord3D\_C16 Pixel Format, bilateral filtering OFF, camera warmed up for 20 minutes.
- Imaging environment: Room light on during testing, black material used to minimize reflections off floor
- Motion stage moved in 50mm steps, for each step measure depth over 10×10 pixel ROI at image center, repeat 32 times at each position
- Accuracy measured as difference between camera's average measured depth across the ROI and 32 images and the ground truth depth (stage zero distance + stage position)

## **Drawings**

#### Helios2 Camera Drawings

